

An Extensible Framework for Modeling Simplicial Complexes

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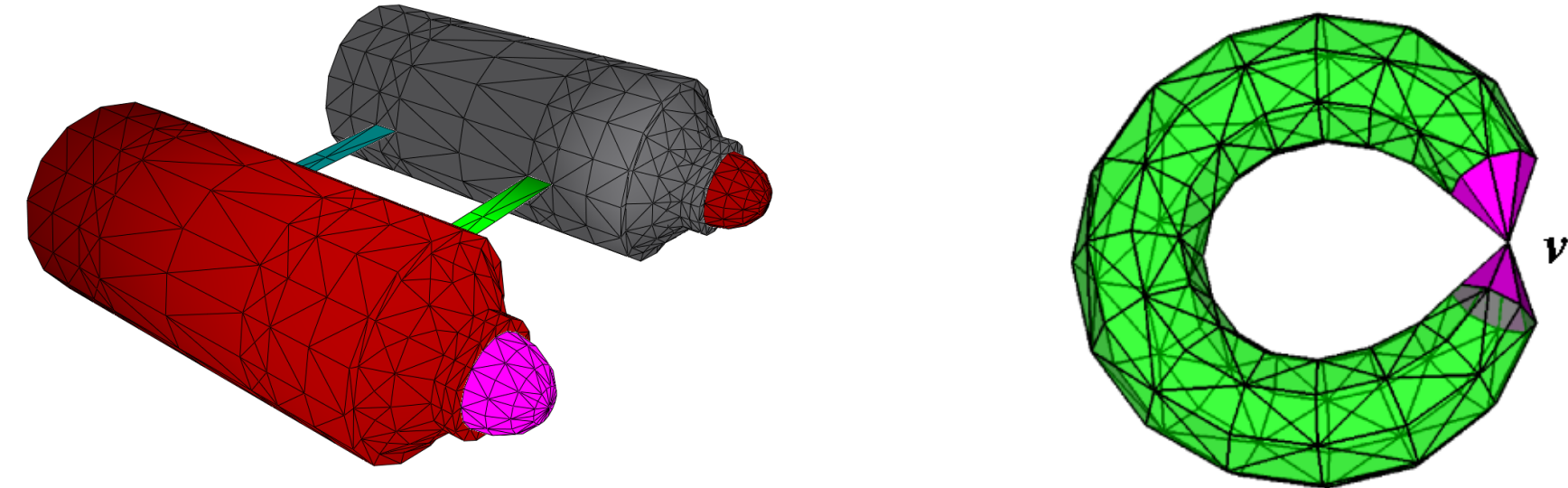
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Problem

- Need to represent *simplicial shapes* of any dimension and with a *complex topology*:
- retrieving *topological information*;
- identifying *non-manifold singularities*.



- Several *data structures* have been developed in the literature [DFH05], also for *non-manifolds*, but they are optimized and restricted to a *specific task*.
- A common framework for their *fast prototyping* is currently lacking, but it would be *interesting* and *suitable* for many applications.

Key Idea

- A framework for this task must satisfy (at least) the following *design choices* [SB11]:
- flexibility**: common representation of any data structure, which can be *dynamically replaced* and *customized* at run-time, if necessary (*plugins*);
- efficiency**: exploit and choose the *most suitable representation* wrt any application need:
 - time efficiency* for topological queries and *restricted storage cost*;
 - expressive power* wrt encoded information;
- easy-to-use**: hide internal details and require a *short learning curve* wrt other tools in the literature.

The Mangrove Topological Data Structure (Mangrove TDS) framework

- We propose the *Mangrove Topological Data Structure (Mangrove TDS)* framework:
 - fast prototyping* of topological data structures for simplicial complexes, described as *mangroves*;
 - implicit representations* of simplices, not encoded in a mangrove, called *ghost simplices*;
 - completely satisfies* all the design choices proposed in [SB11].

Mangroves

- Graph-based representations** of data structures:
 - nodes* correspond to *simplices*, encoded directly in any data structure (possibly not all the simplices);
 - arcs* correspond to *topological relations*, restricted to the subset of simplices directly encoded.
- They can represent *any* topological data structure, also for *non-manifolds*, without restrictions wrt their dimension and the embedding Euclidean space.
- They can be *easily customized* for any modeling need, and dynamically loaded (*plugin*).
- They can encode either all the simplices (*global*), or only a subset (*restricted*).

Ghost Simplices

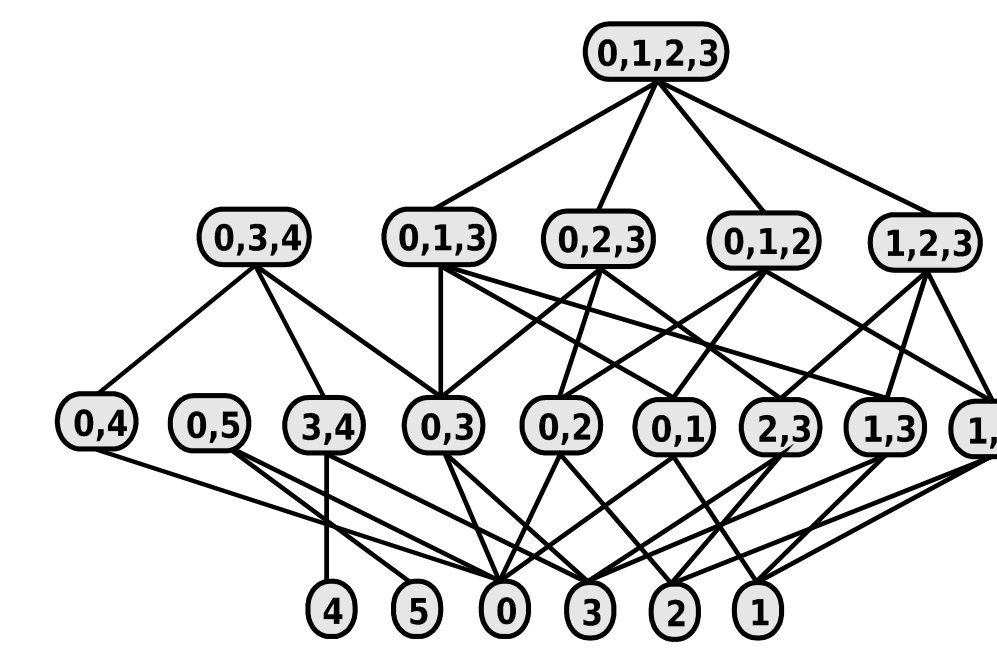
- A p -simplex σ may be either any *top p -simplex*, or a *p -face* of any top k -simplex σ' , and is represented as a 4-tuple (k, i, p, j) , where i is the unique identifier of σ' , and j is the unique identifier of σ as a p -face of σ' .
- Suitable to represent simplices in *high dimensions* (always four values), instead of a variable list of vertices (*explicit representation* of a simplex).
- Make queries **3X faster** for any restricted mangrove, e.g., the IA* data structure [CDFW11], wrt any global mangrove, e.g., the IS data structure [DFHPC10]

Example #1: IS data structure

- Represents *abstract simplicial complexes* of any dimension.
- Encodes *all* simplices.

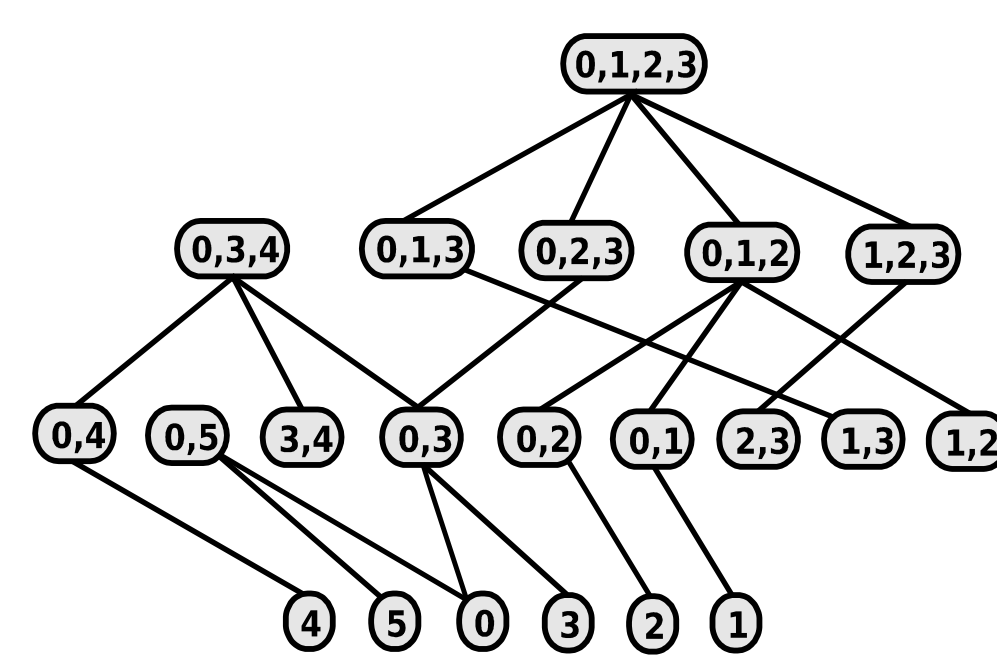
For each p -simplex σ :

- boundary relation $R_{p,p-1}(\sigma)$, formed by $(p-1)$ -simplices on the boundary of σ ;



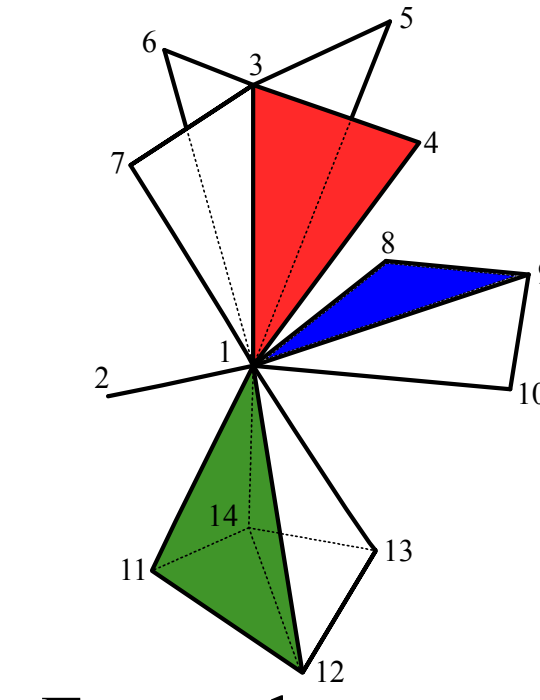
$$R_{3,2}(0,3,4) = \{(0,4); (0,3); (3,4)\}$$

- partial co-boundary relation $R_{p,p+1}^*(\sigma)$, formed by one *arbitrary $(p+1)$ -simplex* for each component in the link of σ .



$$R_{3,4}^*(0) = \{(0,3); (0,5)\}$$

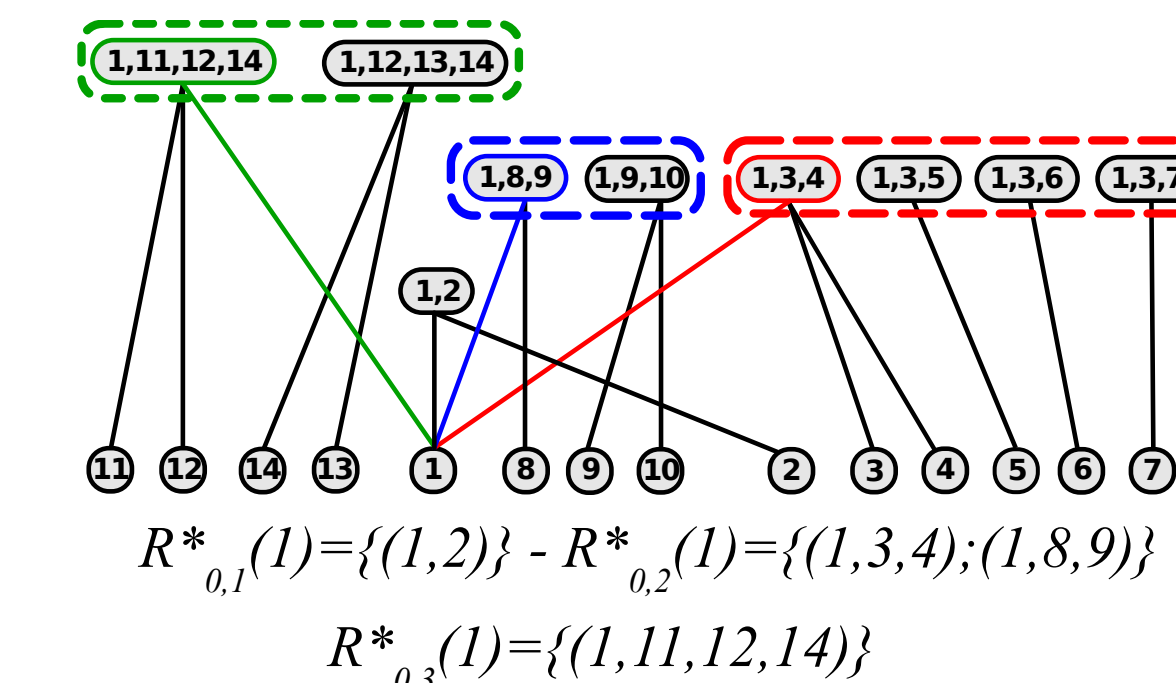
Example #2: IA* data structure



- Represents *abstract simplicial complexes* of any dimension.
- Encodes *vertices* and *top* simplices.

For each vertex v :

- partial co-boundary relation $R_{0,p}^*(v)$: one *arbitrary top p -simplex* for each $(p-1)$ -connected component in the star of v .

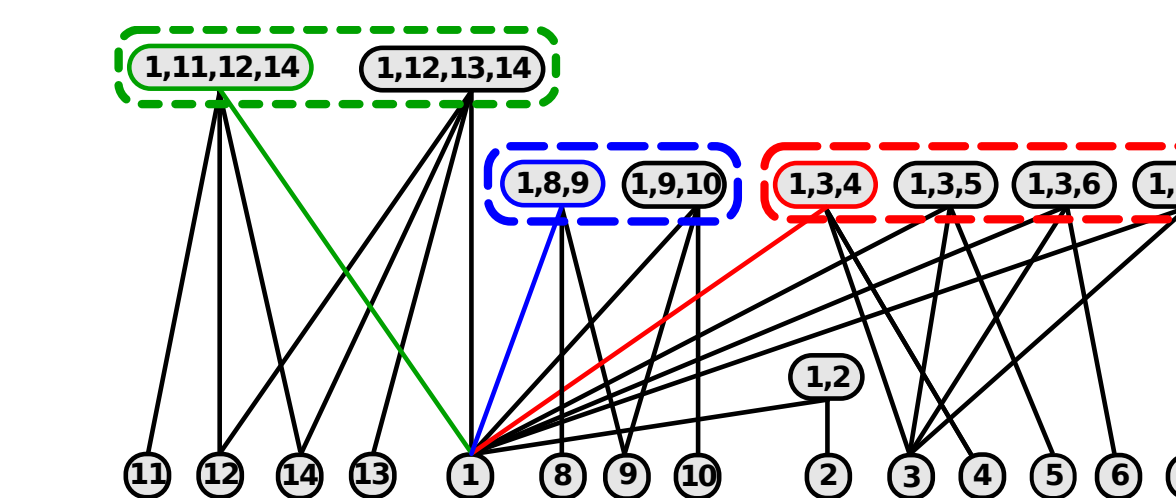


$$R_{0,3}^*(1) = \{(1,2)\} - R_{0,2}^*(1) = \{(1,3,4); (1,8,9)\}$$

$$R_{0,3}^*(1) = \{(1,11,12,14)\}$$

For each top p -simplex σ :

- boundary relation $R_{p,0}(\sigma)$, formed by $p+1$ vertices on the boundary of σ ;



$$R_{1,0}(1,2) = \{1,2\} - R_{2,0}(1,3,4) = \{1,3,4\}, R_{2,0}(1,8,9) = \{1,8,9\}$$

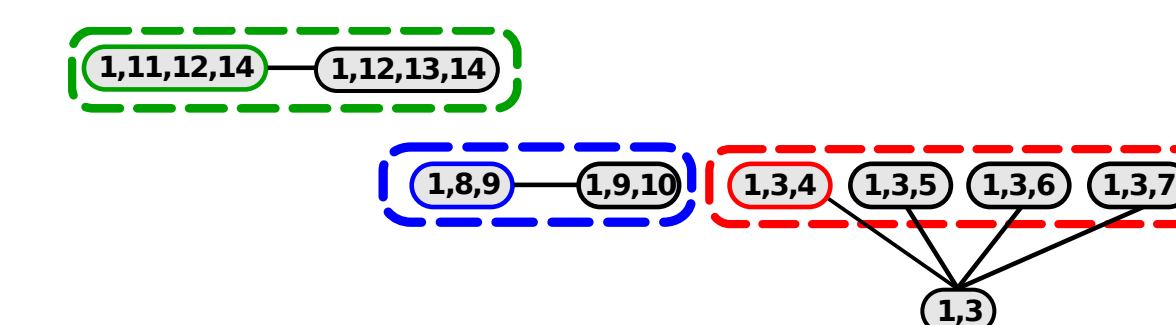
$$R_{3,0}(1,11,12,14) = \{1,11,12,14\}$$

- adjacency relation $R_{p,p}^*(\sigma)$, if $p > 1$, formed by the *top p -simplices* adjacent to σ .

Adjacency relation $R_{p,p}^*(\sigma)$ along a $(p-1)$ -face τ of σ can be *simplified* through relation $R_{p-1,p}^*(\tau)$, formed by top p -simplices incident at τ :

- if τ is on the boundary of *more than two* top p -simplices, then $R_{p-1,p}^*(\tau)$ is stored only once (*non-manifold adjacency*);

- otherwise, a top p -simplex, adjacent to σ , is stored (*manifold adjacency*).



Manifold adjacency along edge $(1,9)$ and triangle $(1,12,14)$.
Non-manifold adjacency along edge $(1,3)$.

Implementation

- The *Mangrove TDS Library* is a C++ tool, which contains the complete implementation of our framework, plus of *six* data structures, including the IS and the IA* data structures.
- It is based on *templated programming* techniques, and is completely *multi-platform*.
- It exploits an *array-based* storage with *iterators* and *garbage collector* for each collections of simplices.
- It is possible to *dynamically* associate *properties* with any simplex, including with *ghost simplices*.
- It is publicly released under *GPL* version 3, visit: <http://mangrovetds.sourceforge.net>
- Our tests show that the IS and IA* data structures are *effective* representations for *non-manifolds* wrt their storage cost, identification of non-manifold simplices, and efficiency of queries.

Current and Future work

- Extensions of the IS and the IA* data structures for *quad* and unstructured *hexahedral meshes*.
- Extensions to *cell complexes* (the Incidence Graph is already in the *Mangrove TDS Library* [Can12]).
- Editing operators* on simplicial and cell complexes: *homology* preserving and modifying operators.

References

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- [SB11] SIEGER D., BOTSCH M., *Design, Implementation, and Evaluation of the Surface_Mesh Data Structure*, 20th International Meshing Roundtable (2011)
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Comparisons with other tools

- Most of other tools exploit a *fixed representation*, which cannot be easily replaced, thus they are *not flexible*.
- The internal representations of some tools are *equivalent* to the *Incidence Graph* [Ede87] and to the *Half-Edge (HE) data structure* [Man88] (see [Can12] for a complete analysis).
- The *HE data structure* and its 3D extensions are *restricted* to the representations of *manifolds*.
- The *Incidence Graph* exhibits a *large overhead* for manifolds, and does *not allow* for the *efficient identification* of non-manifold simplices [DFH05].

	OpenMesh	OpenVolumeMesh	VCGLib	CGAL	Mangrove TDS
Type of Complexes	Cell	Cell	Simplicial	Any	Simplicial
Dimension of Complexes	Up to 2	Up to 3	Up to 3	Any	Any
Internal Representation	Incidence-based	Incidence-based	Adjacency-based	Several	Any
Flexible Representation	No	No	No	Yes (modules)	Yes (plugins)

Funded by Italian Ministry of Education and Research under the PRIN 2009 Program and by National Science Foundation under grant number IIS-1116747.